

/*

--- CAEN SpA - Computing Systems Division ---

Name : CAENVMEDemoVme.c

Project : CaenVmeDemo

Description : Example program for V1718 & V2718 control.

Date : November 2004

Release : 1.0

Author : C.Landi

Date : August 2006

Release : 1.1

Author : NDA

Description : 64 bit porting (CAENVMElib rev >= 2.5)

*/

```
#include <stdlib.h>
#include <stdio.h>
#ifdef LINUX
    #include <inttypes.h>
    #include <stdint.h>
#else
    // From /usr/include/inttypes.h kernel 2.6.15
    #define PRIx32      "X"
    #define PRIu32      "u"
    #define SCNx32      "x"
    #define SCNu32      "u"
#endif
#endif
```

```
#include <math.h>
#include <string.h>
#include <ctype.h>
```

```
#include <stdarg.h>
#include "CAENVMElib.h"
#include "console.h"
```

```
// -----
```

```
// -----
```

```
// X,Y Position for Field display
```

```
// -----
```

```
#define X_ADDR          32
```

```
#define Y_ADDR          9
#define X_BADDR        32
#define Y_BADDR        10
#define X_DSIZE        32
#define Y_DSIZE        11
#define X_AM           32
#define Y_AM           12
#define X_BLTSIZE      32
#define Y_BLTSIZE      13
#define X_AUTOINC      32
#define Y_AUTOINC      14
#define X_NCYCLES      32
#define Y_NCYCLES      15
#define X_COMM         1
#define Y_COMM         21
```

```
// -----
```

```
typedef struct man_par
{
uint32_t    addr ;      // Address
uint32_t    data ;     // Data
ushort     level ;     // Interrupt level
uchar      irqstat;    // IRQ status
ushort     am ;        // Addressing Mode
CVDataWidth dtsize ;   // Data Format
uint32_t    basaddr ;  // Base Address
uint32_t    blts ;     // Block size for blt (bytes)
```

```
ushort      nycyc ;          // Number of cycles
ushort      autoinc ;        // Auto increment address
uint32_t    *buff ;         // Mmemory buffer for blt
} man_par_t ;
```

```
// -----
//  Prototype Functions Declaration
// -----
```

```
void CaenVmeIrqCheck(int32_t, man_par_t *) ;
void CaenVmeWriteBlk(int32_t, man_par_t *) ;
void CaenVmeReadBlk(int32_t, man_par_t *) ;
void CaenVmeWrite(int32_t, man_par_t *) ;
void CaenVmeRead(int32_t, man_par_t *) ;
void ViewReadBlkData(man_par_t *) ;
void CaenVmeManual(int32_t, short) ;
void MarcoVmeWrite(int32_t, man_par_t *, uint32_t) ;
void MarcoVmeRead(int32_t, man_par_t *, uint32_t) ;
```

```
// -----
```

```
/*
```

```
-----
```

Name : CaenVmeIrqCheck

Description : Interrupt Check

Input : BHandle -> Board Id (V1718,V2718)
man -> pointer to 'man' structure
Output : None
Release : 1.0

*/

```
void CaenVmeIrqCheck(int32_t BHandle, man_par_t *man)
{
    CVErrorCodes ret ;

    con_printf(" CHECK IRQ\n");

    CAENVME_IRQCheck(BHandle,&man->irqstat);          // Check IRQ Status

    con_printf(" IRQ status: %02X\n",man->irqstat);
    con_printf(" Interrupt Level to Acknowledge (0 to exit) : "); // Get the int level
    con_scanf("%x",&man->level);

    if (man->level == 0)
    {
        clear_line(Y_COMM);
        clear_line(Y_COMM+1);
        clear_line(Y_COMM+2);
        return ;
    }
}
```

```
con_printf_xy(X_COMM,Y_COMM+2," Waiting for interrupt ... Press any key to stop.");
```

```
while (!(man->irqstat & (1<<(man->level-1))) && !con_kbhit()) // Check Int loop
```

```
    CAENVME_IRQCheck(BHandle,&man->irqstat);
```

```
gotoxy(X_COMM,Y_COMM) ;
```

```
if(man->irqstat & (1<<(man->level-1)))
```

```
{
```

```
    CVIRQLevels level;
```

```
    switch (man->level) {
```

```
        case 1:
```

```
            level = cvIRQ1;
```

```
            break;
```

```
        case 2:
```

```
            level = cvIRQ2;
```

```
            break;
```

```
        case 3:
```

```
            level = cvIRQ3;
```

```
            break;
```

```
        case 4:
```

```
            level = cvIRQ4;
```

```
            break;
```

```
        case 5:
```

```
            level = cvIRQ5;
```

```
            break;
```

```
        case 6:
```

```
            level = cvIRQ6;
```

```
            break;
```

```

case 7:
    level = cvIRQ7;
    break;
default:
    level = cvIRQ1;
    break;
}
ret = CAENVME_IACKCycle(BHandle,level,&man->data,man->dtsize);

switch (ret)
{
    case cvSuccess : con_printf(" Cycle completed normally\n");
                                con_printf(" Int. Ack. on IRQ%d: StatusID = %0X",man-
>level,man->data);
                                break ;
    case cvBusError : con_printf(" Bus Error !!!");
                                break ;
    case cvCommError : con_printf(" Communication Error !!!");
                                break ;
    default : con_printf(" Unknown Error !!!");
                                break ;
}
}
else
    con_printf(" Interrupt request IRQ%d not active",man->level);

```

```
}
```

```
/*
```

```
-----  
Name       :      CaenVmeWriteBlt  
Description :  Vme Block Transfer Write  
  
Input      :      BHandle          ->   Board Id (V1718,V2718)  
           :      man              ->   pointer to 'man' structure  
  
Output     :      None  
Release    :      1.0  
  
-----
```

```
*/
```

```
void CaenVmeWriteBlt(int32_t BHandle, man_par_t *man)
```

```
{
```

```
int          nb;
```

```
uint32_t     i,incr;
```

```
CVAddressModifier am;
```

```
CVErrorCodes ret,old_ret=cvSuccess;
```

```
if(man->am == cvA16_U)
```

```
{
```

```
con_printf(" Can't execute a A16 BLT Write Cycle");
```



```

        return ;
    }
if(man->am == cvCR_CSR)
    {
    con_printf(" Can't execute a CR/CSR BLT Write Cycle");
    return ;
    }

con_printf_xy(X_COMM,Y_COMM+2," First Data [hex] : " ) ;
con_scanf("%x",&man->data); // Get data to write
clear_line(Y_COMM+2) ;
con_printf_xy(X_COMM,Y_COMM+2," Data Increment [hex] : " ) ; // Get increment for data
con_scanf("%x",&incr);
for(i=0; i<(man->blts/4); i++) // Fill the data buffer
    man->buff[i] = man->data+incr*i;

if (man->dtsize == cvD64)
    {
    if (man->am == cvA24_U_DATA)
        am = cvA24_U_MBLT;
    else
        am = cvA32_U_MBLT;
    }
else
    {
    if (man->am == cvA24_U_DATA)
        am = cvA24_U_BLT;
    else
        am = cvA32_U_BLT;
    }

```

```

    }

if(man->ncyc == 0)                                // Infinite Loop
    con_printf_xy(X_COMM,Y_COMM+2," Running ...  Press any key to stop.");

for (i=0; ((man->ncyc==0) || (i<man->ncyc)) && !con_kbhit(); i++)
    {

        ret = CAENVME_BLTWriteCycle(BHandle,man->addr,(char *)man->buff,man->blts,am,man-
        >dtsize,&nb);

        if((i==0) || (ret != old_ret))
            {
                gotoxy(X_COMM,Y_COMM) ;

                switch (ret)
                    {
                        case cvSuccess : con_printf(" Cycle(s) completed normally\n");
                                    con_printf(" Written %u bytes",nb);
                                    break ;

                        case cvBusError : con_printf(" Bus Error !!!\n");
                                    con_printf(" Written %u bytes",nb);
                                    break ;

                        case cvCommError : con_printf(" Communication Error !!!");
                                    break ;

                        default      : con_printf(" Unknown Error !!!");
                                    break ;
                    }
            }
    }

```

```

        old_ret = ret;

    }

if(man->ncyc == 0)
    clear_line(Y_COMM+2);
}

/*
-----

Name      :      CaenVmeReadBlt
Description :  Vme Block Transfer Read

Input     :      BHandle          ->   Board Id (V1718,V2718)
           :      man              ->   pointer to 'man' structure

Output    :      None

Release   :      1.0

-----

*/

void CaenVmeReadBlt(int32_t BHandle, man_par_t *man)
{
int          nb;
uint32_t     i,j;
CVAddressModifier  am;

```

```
CVErrorCodes      ret,old_ret=cvSuccess;
```

```
if(man->am == cvA16_U)
```

```
{
```

```
con_printf(" Can't execute a A16 BLT Read Cycle");
```

```
return ;
```

```
}
```

```
if(man->am == cvCR_CSR)
```

```
{
```

```
con_printf(" Can't execute a CR/CSR BLT Read Cycle");
```

```
return ;
```

```
}
```

```
if (man->dtsize == cvD64)
```

```
{
```

```
if (man->am == cvA24_U_DATA)
```

```
am = cvA24_U_MBLT;
```

```
else
```

```
am = cvA32_U_MBLT;
```

```
}
```

```
else
```

```
{
```

```
if (man->am == cvA24_U_DATA)
```

```
am = cvA24_U_BLT;
```

```
else
```

```
am = cvA32_U_BLT;
```

```
}
```

```

if(man->ncyc == 0)                                // Infinite Loop
    con_printf_xy(X_COMM,Y_COMM+2," Running ...  Press any key to stop.");

for (i=0; ((man->ncyc==0) || (i<man->ncyc)) && !con_kbhit(); i++)
    {
    for (j=0;j<(man->blts/4);j++)
        man->buff[j]=0;

    ret = CAENVME_BLTReadCycle(BHandle,man->addr,(char *)man->buff,man->blts,am,man-
>dtsize,&nb);

    if((i==0) || (ret != old_ret))
        {
        gotoxy(X_COMM,Y_COMM) ;

        switch (ret)
            {
            case cvSuccess  : con_printf(" Cycle(s) completed normally\n");
                                con_printf(" Read b% bytes\n");
                                break ;

            case cvBusError : con_printf(" Bus Error !!!\n");
                                con_printf(" Read b% bytes\n");
                                break ;

            case cvCommError : con_printf(" Communication Error !!!");
                                break ;

            default      : con_printf(" Unknown Error !!!");
                                break ;

            }

        }
    }

```

```

        old_ret = ret;

    }

if(man->ncyc == 0)
    clear_line(Y_COMM+2);
}

/*
-----

Name      :      CaenVmeWrite
Description :  Vme Write access

Input      :      BHandle          ->   Board Id (V1718,V2718)
              man                  ->   pointer to 'man' structure

Output     :      None

Release    :      1.0

-----

*/

void CaenVmeWrite(int32_t BHandle, man_par_t *man)
{
uint32_t      i;
CVErrorCodes ret,old_ret=cvSuccess;

```

```

if(man->dtsize == cvD64)
    {
    con_printf(" Can't execute a D64 Write Cycle");
    return ;
    }

con_printf_xy(X_COMM,Y_COMM+1," Write Data [hex] : " ) ;
con_scanf("%x",&man->data) ;

if(man->ncyc == 0)                                // Infinite Loop
    con_printf_xy(X_COMM,Y_COMM+2," Running ...  Press any key to stop.");

for (i=0; ((man->ncyc==0) || (i<man->ncyc)) && !con_kbhit(); i++)
    {

    ret = CAENVME_WriteCycle(BHandle,man->addr,&man->data,man->am,man->dtsize);

    if((i==0) || (ret != old_ret))
        {
        gotoxy(X_COMM,Y_COMM) ;

        switch (ret)
            {
            case cvSuccess : con_printf(" Cycle(s) completed normally\n");
                            break ;
            case cvBusError : con_printf(" Bus Error !!!");
                            break ;
            }
        }
    }

```

```

        case cvCommError : con_printf(" Communication Error !!!");
                                break ;

        default      : con_printf(" Unknown Error !!!");
                                break ;

    }

}

old_ret = ret;

if(man->autoinc)
{
    man->addr += man->dtsize;          // Increment address (+1 or +2 or +4)
    con_printf_xy(X_ADDR,Y_ADDR,"%08X]",man->addr); // Update the screen
}

}

if(man->ncyc == 0)
    clear_line(Y_COMM+2);
}

////////////////////
////////////////////
////////////////////
/* MARCO FUNCTION: WRITE SOMETHING IN HEX TO A GIVEN ADDRESS */
////////////////////
////////////////////
////////////////////

void MarcoVmeWrite(int32_t BHandle, man_par_t *man, uint32_t marco_data)
{

```



```

uint32_t          i;
CVMErrorCodes    ret,old_ret=cvSuccess;

if(man->dtsize == cvD64)
    {
    con_printf(" Can't execute a D64 Write Cycle");
    return ;
    }

//con_printf_xy(X_COMM,Y_COMM+1," Write Data [hex] : ");
//con_scanf("%x",&man->data) ;

if(man->ncyc == 0)                // Infinite Loop
    con_printf_xy(X_COMM,Y_COMM+2," Running ...  Press any key to stop.");

for (i=0; ((man->ncyc==0) || (i<man->ncyc)) && !con_kbhit(); i++)
    {

//    ret = CAENVME_WriteCycle(BHandle,man->addr,&man->data,man->am,man->dtsize);
    ret = CAENVME_WriteCycle(BHandle,man->addr,&marco_data,man->am,man->dtsize);

    if((i==0) || (ret != old_ret))
        {
        gotoxy(X_COMM,Y_COMM) ;

        switch (ret)

```

```

        {
        case cvSuccess : con_printf(" Cycle(s) completed normally\n");
                                break ;
        case cvBusError : con_printf(" Bus Error !!!");
                                break ;
        case cvCommError : con_printf(" Communication Error !!!");
                                break ;
        default : con_printf(" Unknown Error !!!");
                                break ;
        }
    }

old_ret = ret;

if(man->autoinc)
    {
    man->addr += man->dtsize;          // Increment address (+1 or +2 or +4)
    con_printf_xy(X_ADDR,Y_ADDR,"%08X",man->addr); // Update the screen
    }
}

if(man->ncyc == 0)
    clear_line(Y_COMM+2);
}

/*
-----

```

Name : CaenVmeRead

Description : Vme Read access

Input : BHandle -> Board Id (V1718,V2718)
man -> pointer to 'man' structure

Output : None

Release : 1.0

*/

```
void CaenVmeRead(int32_t BHandle, man_par_t *man)
```

```
{
```

```
uint32_t i,old_data=0;
```

```
CVErrorCodes ret,old_ret=cvSuccess;
```

```
if(man->dtsize == cvD64)
```

```
{
```

```
con_printf(" Can't execute a D64 Read Cycle");
```

```
return ;
```

```
}
```

```
if(man->ncyc == 0) // Infinite Loop
```

```
con_printf_xy(X_COMM,Y_COMM+2," Running ... Press any key to stop.");
```

```
for (i=0; ((man->ncyc==0) || (i<man->ncyc)) && !con_kbhit(); i++)
```

```
{
```

```

ret = CAENVME_ReadCycle(BHandle,man->addr,&man->data,man->am,man->dtsize);
// ret = CAENVME_ReadCycle(BHandle,man->addr,&marco_data,man->am,man->dtsize);
if((i==0) || (ret != old_ret))
{
gotoxy(X_COMM,Y_COMM) ;

switch (ret)
{
case cvSuccess : con_printf(" Cycle(s) completed normally\n");
if((i==0) || (old_data != man->data))
{
if( man->dtsize == cvD32 )
con_printf(" Current Value :
%08d\n",man->data);
//voltage uses this if statement
if( man->dtsize == cvD16 )
con_printf(" Current Value :
%04d\n",man->data & 0xffff);
if( man->dtsize == cvD8 )
con_printf(" Current Value :
%02d\n",man->data & 0xff);
}
break ;
case cvBusError : con_printf(" Bus Error !!!");
break ;
case cvCommError : con_printf(" Communication Error !!!");
break ;
default : con_printf(" Unknown Error !!!");
break ;
}
}

```

```

        }

old_data = man->data;
old_ret = ret;

if(man->autoinc)
    {
        man->addr += man->dtsize;           // Increment address (+1 or +2 or +4)
        con_printf_xy(X_ADDR,Y_ADDR,"%08X]",man->addr); // Update the screen
    }
}

if(man->ncyc == 0)
    clear_line(Y_COMM+2);
}

```

/*

Name : ViewReadBlitData

Description : Display the content of 'man->buff' buffer

Input : man -> pointer to 'man' structure

Output : None

Release : 1.0

*/

```
void ViewReadBlkData(man_par_t *man)
```

```
{
```

```
  ushort      i,j,line, page=0, gotow, dtsize ;
```

```
  uint32_t    ndata;
```

```
  uint32_t    *d32;
```

```
  ushort      *d16;
```

```
  uchar       *d8;
```

```
  char        key = 0;
```

```
  char        msg[80];
```

```
  FILE        *fsave;
```

```
  d32 = man->buff ;
```

```
  d16 = (ushort *)man->buff ;
```

```
  d8 = (uchar *)man->buff ;
```

```
  dtsize = man->dtsize ;
```

```
  while( key != 'Q' )                // Loop. Exit if 'Q' is pressed
```

```
  {
```

```
    ndata = man->blts / dtsize;
```

```
    clrscr() ;
```

```
    con_printf("\n VIEW BUFFER\n\n") ;
```

```
    con_printf(" Num.  Addr  Hex   Dec \n\n");
```

```
    // Write a page
```

```

for( line=0, i=page * 16; (line<16) && (i<ndata); line++, i++)
    {
    if( dtsize == cvD32 || dtsize == cvD64)
        con_printf(" %05u %04X %08X %-10d \n",i,i*4,d32[i],d32[i]);

    if( dtsize == cvD16)
        con_printf(" %05u %04X %04X %-6d \n",i,i*2,d16[i],d16[i]);

    if( dtsize == cvD8)
        con_printf(" %05u %04X %02X %-4d \n",i,i,d8[i],d8[i]);
    }

        // Print the line menu
con_printf("\n[Q] Quit [D] Data_size [S] Save [G] Goto");
if( page != 0 )
    con_printf(" [P] Previous");
if( i != ndata )
    con_printf(" [N] Next");

    key=toupper(con_getch()); // Wait for command

clear_line(22);

switch (key)
    {
    case 'N' :    if(i<ndata) // Next page
                    page++;
                    break ;
    case 'P' :    if(page>0) // Previous page

```

```

        page--;
        break ;
case 'D' :    dtsize = dtsize * 2; // Change data size (8,16,32)
              if(dtsize > 4)
                dtsize = 1;
              page = 0;
              break ;
case 'G' :    con_printf("Insert data number (dec) : ") ; // Go to data
              con_scanf("%d",(ushort *)&gotow) ;

              if(gotow>ndata)
                {
                  clear_line(22) ;
                  con_printf(" Invalid data number ");
                }
              else
                page=gotow/16;
              break ;

case 'S' :    clear_line(23) ;
              con_printf_xy(1,23," File Name : ") ; // Save buffer to file
              if (con_scanf("%s",msg) == EOF)
                break ;

              if((fsave=fopen(msg,"w")) == NULL)
                {
                  clear_line(23) ;
                  con_printf_xy(1,23," Can't open file ");
                }

```



```
        else
            {
                for(j=0;j<ndata;j++)
            {
                if( dtsize == cvD32 || dtsize == cvD64)
                    fprintf(fsave,"%05u\t%08X\t%-10d\n",j,d32[j],d32[j]);
                if( dtsize == cvD16)
                    fprintf(fsave,"%05u\t%04X\t%-6d\n",j,d16[j],d16[j]);
                if( dtsize == cvD8)
                    fprintf(fsave,"%05u\t%02X\t%-4d\n",j,d8[j],d8[j]);
            }

                fclose(fsave);
            }
        break ;

    default : break ;

    }
}
}
```

```
////////////////////////////////////
////////////////////////////////////
//MarcoVmeread////////////////////////////////////
//by will lash
////////////////////////////////////
```

```
void MarcoVmeRead(int32_t BHandle, man_par_t *man, uint32_t marco_data)
```



```

                                con_printf(" Current value :
%08d",man->data);
                                if( man->dtsize == cvD16 )
                                con_printf(" Current value :
%04d",man->data & 0xffff);
                                if( man->dtsize == cvD8 )
                                con_printf(" Current value :
%02d",man->data & 0xff);
                                }
                                break ;
                                case cvBusError : con_printf(" Bus Error !!!");
                                break ;
                                case cvCommError : con_printf(" Communication Error !!!");
                                break ;
                                default      : con_printf(" Unknown Error !!!");
                                break ;
                                }
                                }

                                old_data = man->data;
                                old_ret = ret;

                                if(man->autoinc)
                                {
                                    man->addr += man->dtsize;          // Increment address (+1 or +2 or +4)
                                    con_printf_xy(X_ADDR,Y_ADDR,"%08X",man->addr); // Update the screen
                                }
                                }

```

```

if(man->ncyc == 0)

```

```

clear_line(Y_COMM+2);
}

/*
-----

Name      :      CaenVmeManual
Description :  V1718 & v2718 manual controller

Input      :      BHandle          ->   Board Id (V1718,V2718)
              first_call          ->   flag for default settings

Output     :      None

Release    :      1.0

-----

*/

void CaenVmeManual(int32_t BHandle, short first_call)
{

static man_par_t    man    ;
char                key,dis_main_menu ;
uint32_t            value ;

uint32_t channel_base_address;
int ij;
float val;

```

```

if (first_call)
    {
        // Default Value
        man.addr = 0;
        man.level = 1 ;
        man.am = cvA32_U_DATA ;
        man.dtsize = cvD16 ;
        man.basaddr = 0x32100000;//839909376 ;
        man.blts = 256 ;
        man.ncyc = 1 ;
        man.autoinc = 0 ;

        // Allocate 32K for the software buffer containing data for blt

man.buff = (uint32_t *)malloc(16*1024*1024);
if (man.buff == NULL)
    {
        con_printf(" !!! Error. Can't allocate memory for BLT buffer. ");
        exit(-1);
    }
}

for (;;)
    {
        dis_main_menu = 0 ;

        clrscr() ;

        dis_main_menu = 0 ;

```

```

con_printf("\n  CAEN VME Manual Controller \n\n");

con_printf(" R - READ\n");
con_printf(" W - WRITE\n");
con_printf(" B - BLOCK TRANSFER READ\n");
con_printf(" T - BLOCK TRANSFER WRITE\n");
con_printf(" I - CHECK INTERRUPT\n");
con_printf(" 1 - ADDRESS          [%08"PRIX32"]\n",man.addr) ;
con_printf(" 2 - BASE ADDRESS        [%08"PRIX32"]\n",man.basaddr) ;
con_printf(" 3 - DATA FORMAT          [");
if (man.dtsize == cvD8)
    con_printf("D8]\n");
if (man.dtsize == cvD16)
    con_printf("D16]\n");
if (man.dtsize == cvD32)
    con_printf("D32]\n");
if (man.dtsize == cvD64)
    con_printf("D64]\n");

con_printf(" 4 - ADDRESSING MODE      [");
if (man.am == cvA16_U)
    con_printf("A16]\n");
if (man.am == cvA24_U_DATA)
    con_printf("A124]\n");
if (man.am == cvA32_U_DATA)
    con_printf("A32]\n");
if (man.am == cvCR_CSR)
    con_printf("CR/CSR]\n");

```

```
con_printf(" 5 - BLOCK TRANSFER SIZE    [%"PRIu32"]\n",man.blts) ;
con_printf(" 6 - AUTO INCREMENT ADDRESS  [");
if (man.autoinc)
    con_printf("ON] \n");
else
    con_printf("OFF]\n");

con_printf(" 7 - NUMBER OF CYCLES      [");
if (man.ncyc)
    con_printf("%d]\n",man.ncyc) ;
else
    con_printf("Infinite\n");

con_printf(" 8 - VIEW BLT DATA\n");
con_printf(" F - FRONT PANEL I/O\n");
con_printf(" Q - QUIT MANUAL CONTROLLER\n");

con_printf("\n 0 - Interactive menu\n");

do
{
    gotoxy(X_COMM,Y_COMM) ;

    key = toupper(con_getch()) ;

    clear_line(Y_COMM) ;
    clear_line(Y_COMM+1) ;
    clear_line(Y_COMM+2) ;
```

```
gotoxy(X_COMM,Y_COMM) ;
```

```
switch (key)
```

```
{
```

```
case 'R' : CaenVmeRead(BHandle, &man) ;
```

```
break ;
```

```
case 'W' : CaenVmeWrite(BHandle, &man) ;
```

```
break ;
```

```
case 'B' : CaenVmeReadBlk(BHandle, &man) ;
```

```
break ;
```

```
case 'T' : CaenVmeWriteBlk(BHandle, &man) ;
```

```
break ;
```

```
case 'I' : CaenVmeIrqCheck(BHandle, &man) ;
```

```
break ;
```

```
case '1' : con_printf(" Please enter new Address : ") ;
```

```
if (con_scanf("%"SCNx32,&value) != EOF)
```

```
man.addr = man.basaddr + value ;
```

```
con_printf_xy(X_ADDR,Y_ADDR,"%08"PRIx32,man.addr) ;
```

```
clear_line(Y_COMM) ;
```

```
break ;
```



```
/*
if (man.addr = 000000000);
{man.addr = 321000090;};
break;
if (man.addr = 111111111);
{man.addr = 321000110;};
break;
if (man.addr = 222222222);
{man.addr = 321000190;};
break;
if (man.addr = 333333333);
{man.addr = 321000210;};
break;
if (man.addr = 444444444);
{man.addr = 321000290;};
break;
if (man.addr = 555555555);
{man.addr = 321000310;};
break;
*/
```

```
case '2': con_printf(" Please enter new Base Address : ");
```

```
if (con_scanf("%"SCNx32,&value) != EOF)
```

```
{
```

```
man.addr -= man.basaddr ;
```

```
man.basaddr = value ;
```

```
man.addr += man.basaddr ;
```

```
}
```

```
con_printf_xy(X_BADDR,Y_BADDR,"%08"PRIX32,man.basaddr);
```

```
con_printf_xy(X_ADDR,Y_ADDR,"%08"PRIX32,man.addr);
```

```
clear_line(Y_COMM);
```

```
break;
```

```
case '3': gotoxy(X_DSIZE,Y_DSIZE);
```

```
switch(man.dtsize)
```

```
{
```

```
case cvD8 : man.dtsize = cvD16;
```

```
con_printf("D16]\n");
```

```
break;
```

```
case cvD16 : man.dtsize = cvD32;
```

```
con_printf("D32]\n");
```

```
break;
```

```
case cvD32 : man.dtsize = cvD64;
```

```
con_printf("D64]\n");
```

```
break;
```

```
case cvD64 : man.dtsize = cvD8;
```

```
con_printf("D8] \n");
```

```
break;
```

```
case cvD16_swapped :
```



```

        break ;

case '5' : con_printf(" Please enter Block Transfer Size : ");

        if (con_scanf("%"SCNu32,&value) != EOF)
            man.blts = value ;
        con_printf_xy(X_BLTSIZE,Y_BLTSIZE,"%"PRIu32"]
\n",man.blts) ;

        clear_line(Y_COMM) ;

        break ;

case '6' : gotoxy(X_AUTOINC,Y_AUTOINC) ;

        man.autoinc ^= 1 ;
        if (man.autoinc)
            con_printf("ON] \n") ;
        else
            con_printf("OFF]\n") ;

        break ;

case '7' : con_printf(" Please enter Number of Cycles : ");

        if (con_scanf("%"SCNu32,&value) != EOF)
            man.ncyc = (ushort)value ;
        gotoxy(X_NCYCLES,Y_NCYCLES) ;

```

```

        if (man.ncyc)
            con_printf("%"PRIu32"] \n",man.ncyc) ;
        else
            con_printf("Infinite]\n",man.ncyc) ;

        clear_line(Y_COMM) ;

        break ;

    case '8' :    ViewReadBlitData(&man);
                dis_main_menu = 1;    // Display Main Menu
                break ;

    case 'Q' : free(man.buff);          // Release the memory buffer for BLT
                return ;

    case '0' : con_printf(" Which channel do you want to work with? (0..5)\n");
con_printf("Enter desired Channel:");
if(con_scanf("%"SCNx32,&value) != EOF) {
    switch (value) {
        case 0 : channel_base_address = 0x80;
                break;
        case 1 : channel_base_address = 0x100;
                break;
        case 2 : channel_base_address = 0x180;
                break;
        case 3 : channel_base_address = 0x200;
                break;
        case 4 : channel_base_address = 0x280;

```

```

        break;
    case 5 : channel_base_address = 0x300;
        break;
// make the other cases for each channel
        default : break;
    }
}

con_printf(" What do you want to do with channel %d?\n",value);
con_printf(" -> 0 - OFF\n");
con_printf(" -> 1 - ON\n");
con_printf(" -> 2 - Change voltage\n");
con_printf(" -> 3 - Change current\n");
con_printf("Enter choice:");
// Read voltage set
// Read voltage monitor

//.... Write down all the other options

if(con_scanf("%"SCNx32,&value) != EOF) {
    switch (value) {
        case 0 :
            man.addr = man.basaddr + channel_base_address + 0x10;
            con_printf_xy(X_ADDR,Y_ADDR,"%08"PRIx32,man.addr) ;
            MarcoVmeWrite(BHandle, &man, 0);
            //con_printf("Channel %d Off\n");
            // delay(1000);
            break;
        case 1 :

```

```

        man.addr = man.basaddr + channel_base_address + 0x10;
        con_printf_xy(X_ADDR,Y_ADDR,"%08"PRIx32,man.addr) ;
        MarcoVmeWrite(BHandle, &man, 1);
// con_printf("Channel %d On\n");
// delay(1000);
        break;
    case 2 :
clear_line(Y_COMM);
        man.addr = man.basaddr + channel_base_address + 0x00;
//        con_printf_xy(X_ADDR,Y_ADDR,"%08"PRIx32,man.addr) ;
        CaenVmeRead(BHandle, &man);
        con_printf("Input voltage: ");
        if(con_scanf("%f",&val) != EOF) {
            value = (int)(val*10);
//            con_printf("Typed: %d",value);
            MarcoVmeWrite(BHandle, &man, value);
break;
    case 3 :
        man.addr = man.basaddr + channel_base_address + 0x04;
//        con_printf_xy(X_ADDR,Y_ADDR,"%08"PRIx32,man.addr) ;
        CaenVmeRead(BHandle, &man);
        con_printf("Input Current:\n ");
        if(con_scanf("%f",&val) != EOF) {
            value = (int)(val);
//            con_printf("Typed: %d",value);
            MarcoVmeWrite(BHandle, &man, value);
        }
    }
break;

```

```

        // ADD OTHER CASES!
        default : break;
    }
}

/*    if(value == 1) {
        man.addr = man.basaddr + 144;
        con_printf_xy(X_ADDR,Y_ADDR,"%08"PRIx32,man.addr) ;
        MarcoVmeWrite(BHandle, &man, 1);
    }
*/
for(ii=0; ii<10; ii++) clear_line(Y_COMM+ii) ;
break ;

        default : break ;
    }

    }
while (!dis_main_menu) ;

}
// End 'for(;;)'
}

```